

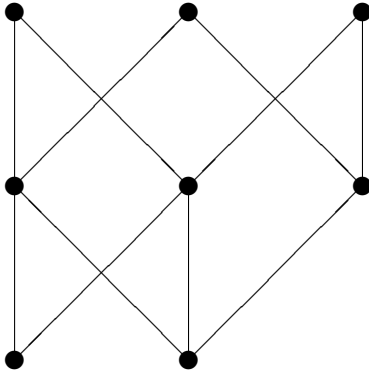
Using Algebraic Topology to Prove Performance Guarantees for a Constraint Satisfaction Algorithm?

Bernd Schröder

Definition.

Definition. *An ordered set is a pair (P, \leq) of a set P and a reflexive, antisymmetric and transitive relation \leq , the order relation.*

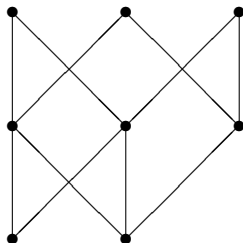
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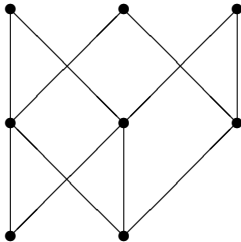
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Definition. A function from an ordered set (P, \leq) to another ordered set (Q, \leq) is called **order-preserving** iff, for all $x, y \in P$ we have that $x \leq y$ implies $f(x) \leq f(y)$.

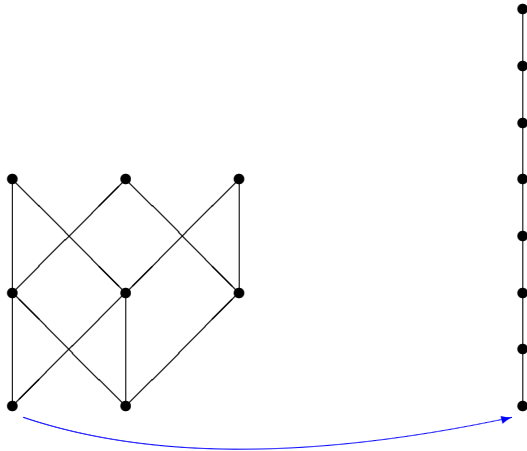
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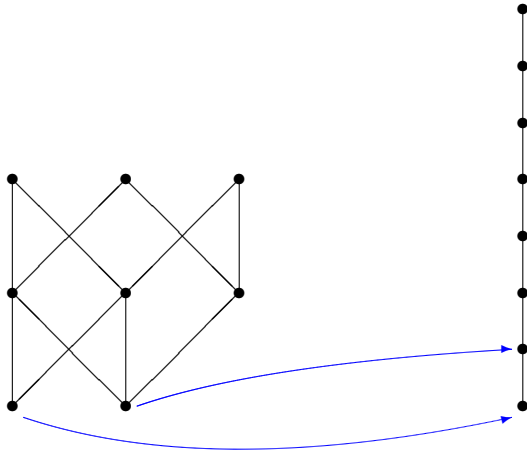
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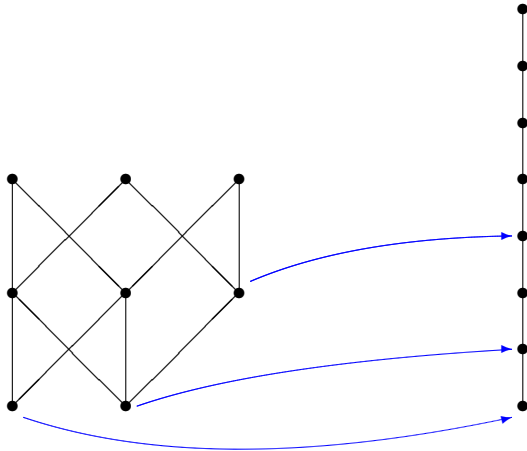
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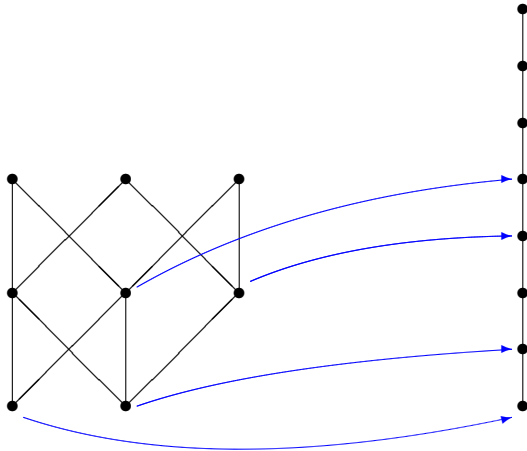
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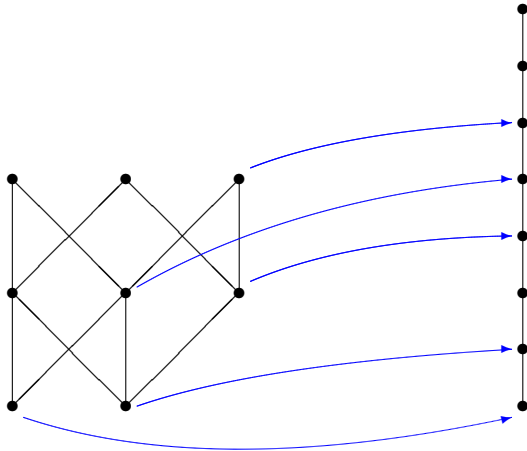
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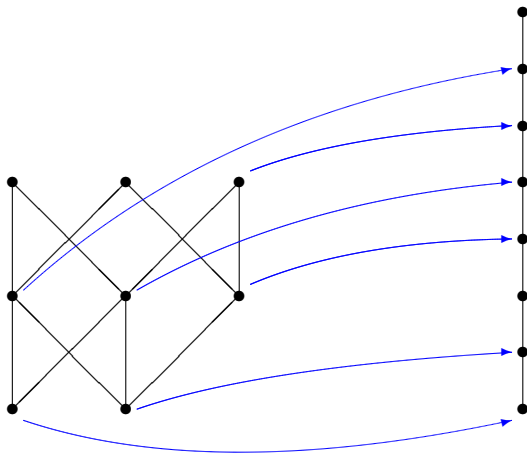
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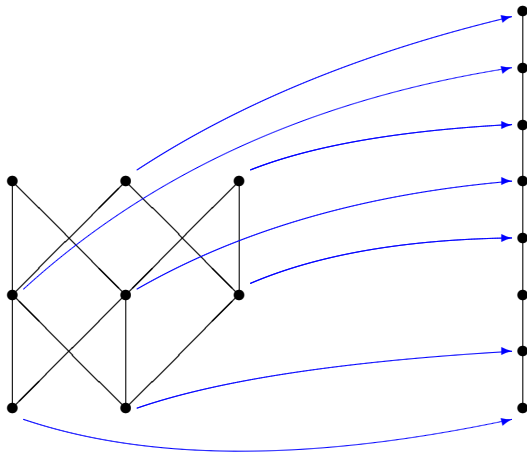
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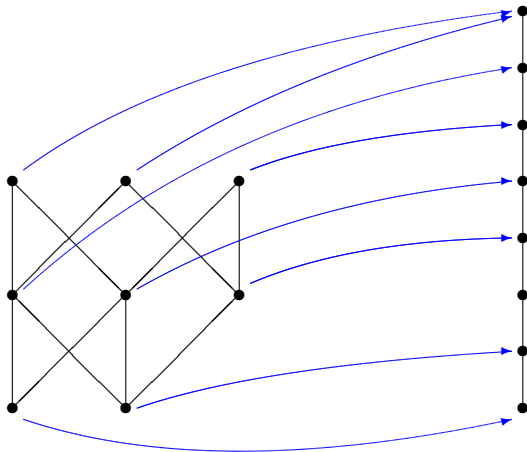
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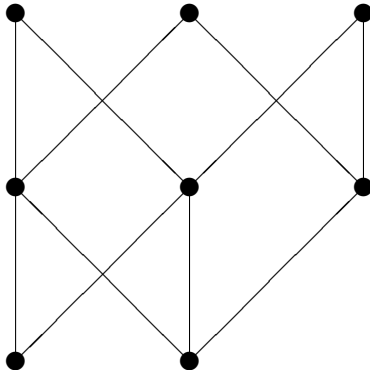
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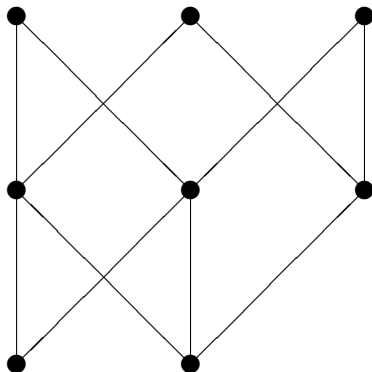
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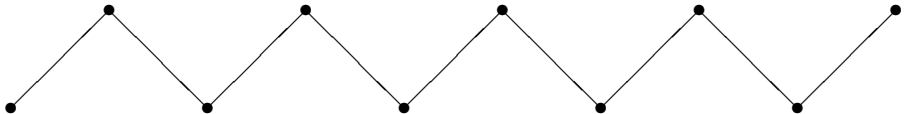
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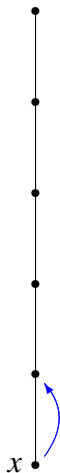
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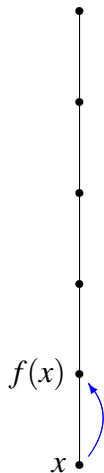
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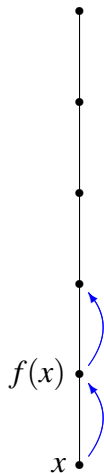
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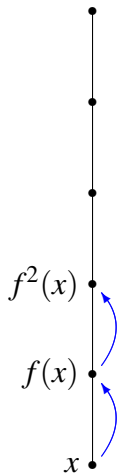
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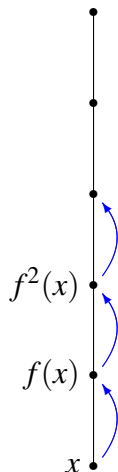
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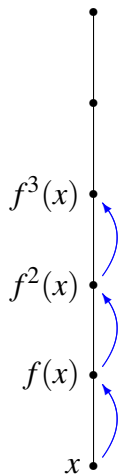
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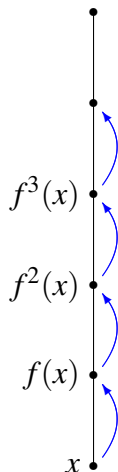
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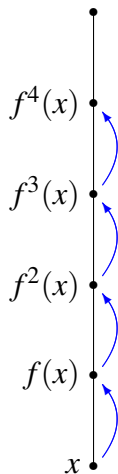
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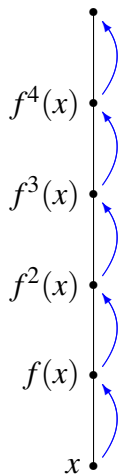
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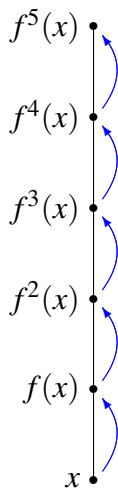
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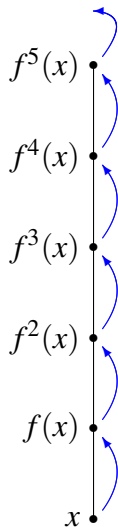
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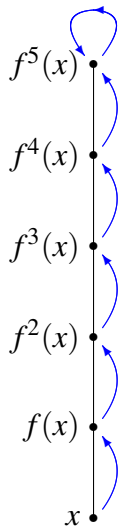
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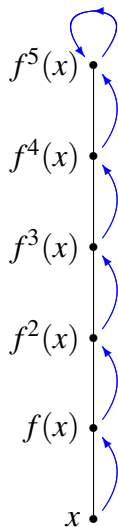


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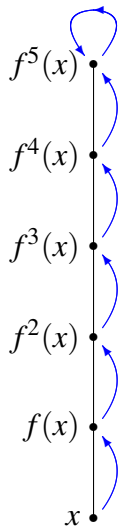


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Theorem.

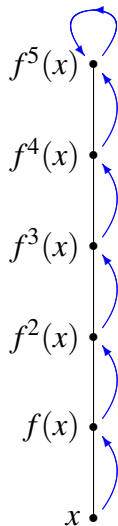


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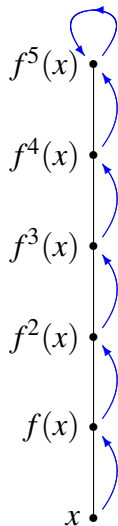
Theorem. *The Abian–Brown Theorem.*

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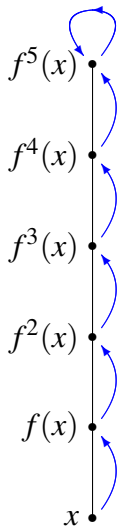
Theorem. *The Abian–Brown Theorem. Let P be a chain-complete ordered set and let $f : P \rightarrow P$ be order-preserving.*

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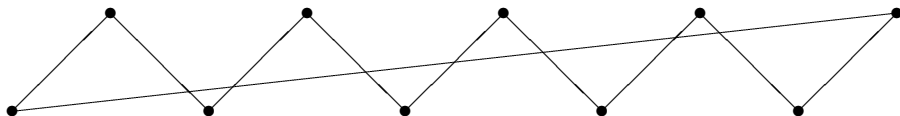
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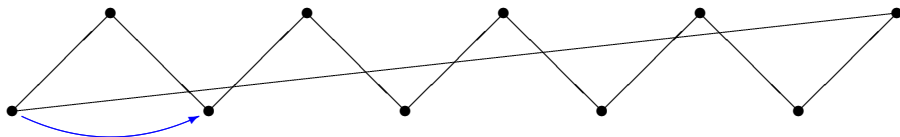
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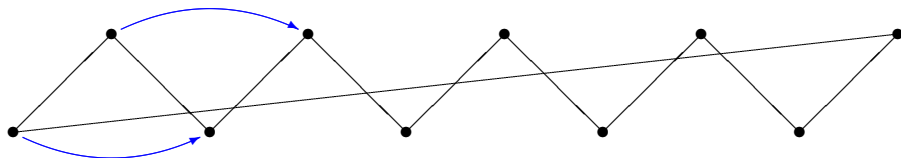
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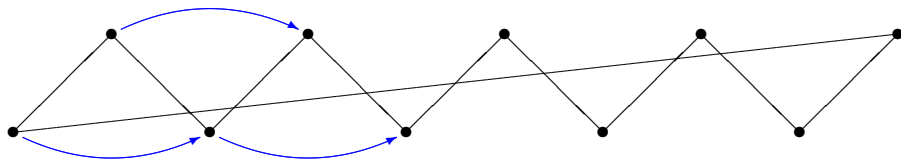
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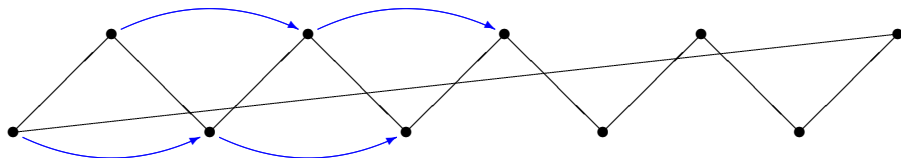
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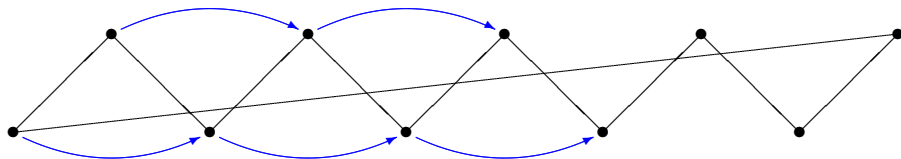
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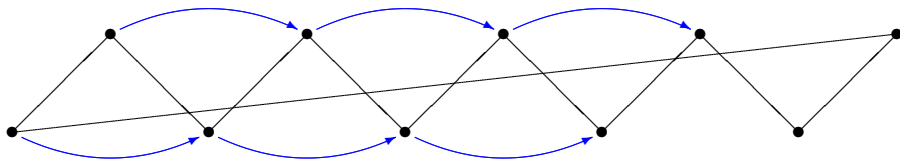
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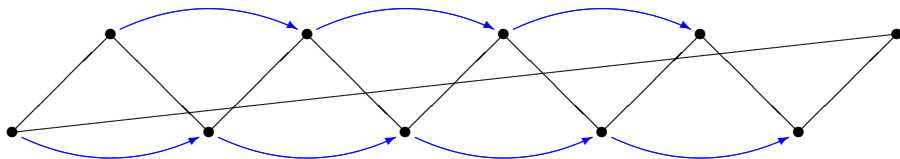
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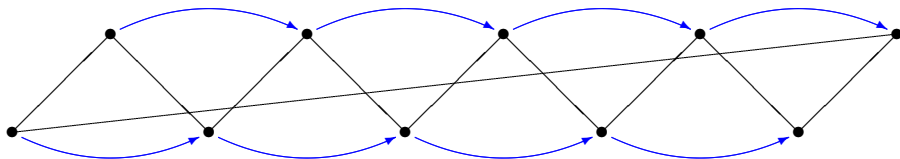
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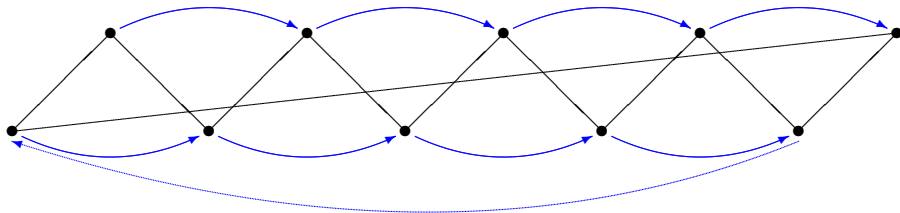
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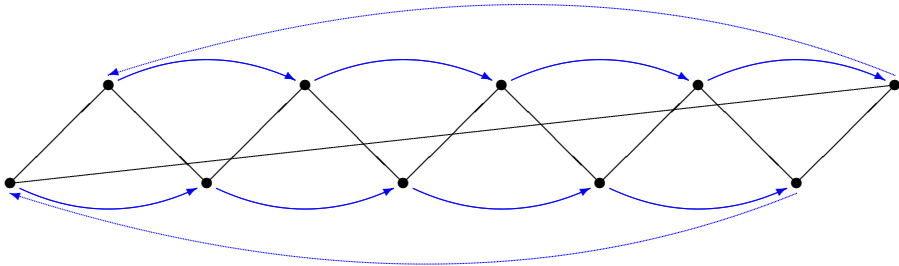
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Proof. Let $f : r[P] \rightarrow r[P]$ be order-preserving. Then $f \circ r : P \rightarrow P$ is order-preserving, too, and hence it has a fixed point $x = f(r(x))$. But then $x \in f[P] \subseteq r[P]$ and hence $x = r(x)$, which means that $x = f(r(x)) = f(x)$ is a fixed point of f . ■

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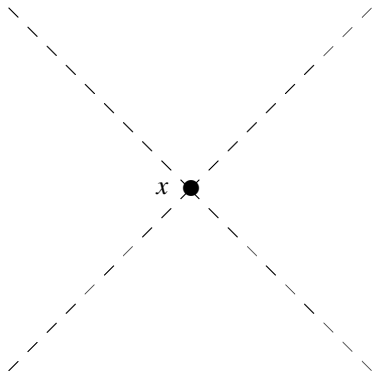
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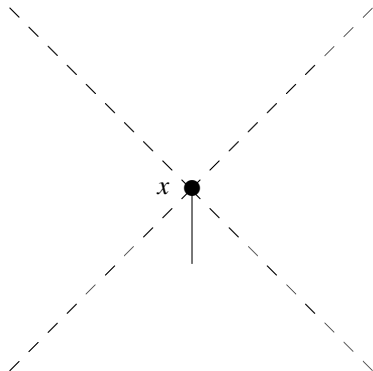
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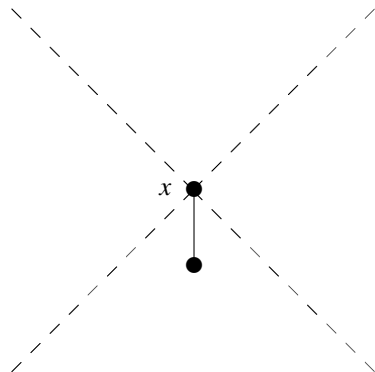
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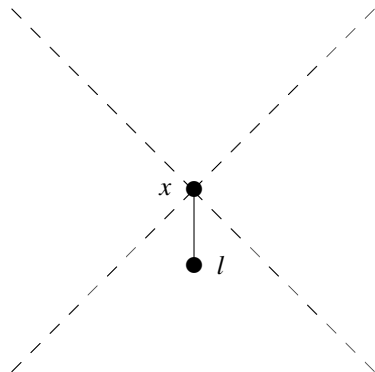
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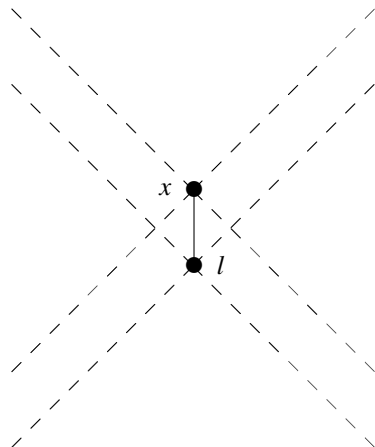
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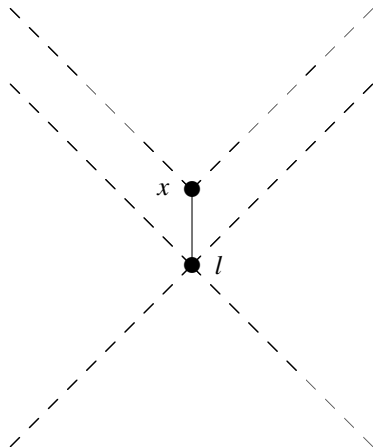
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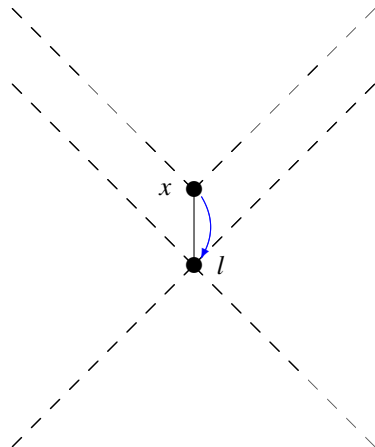
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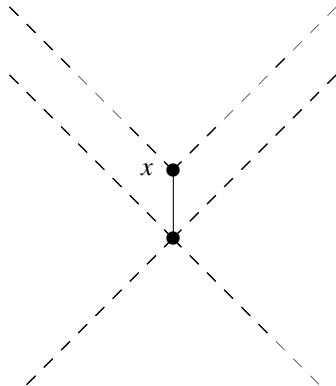
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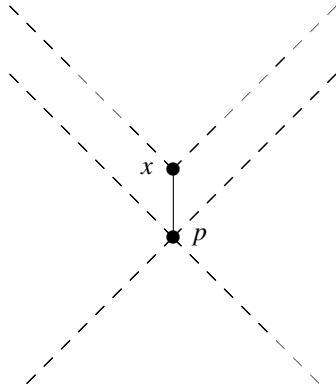
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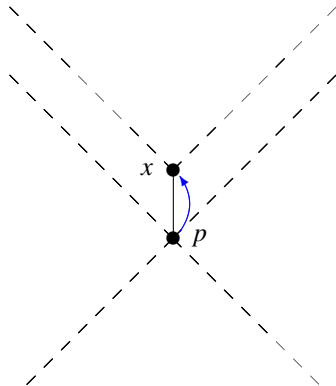
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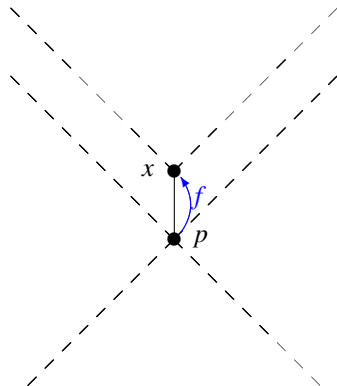
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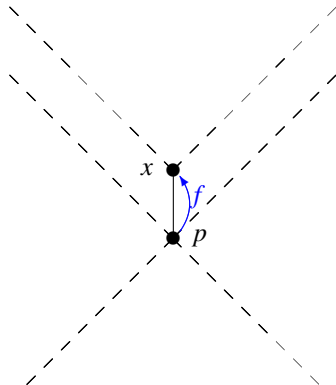
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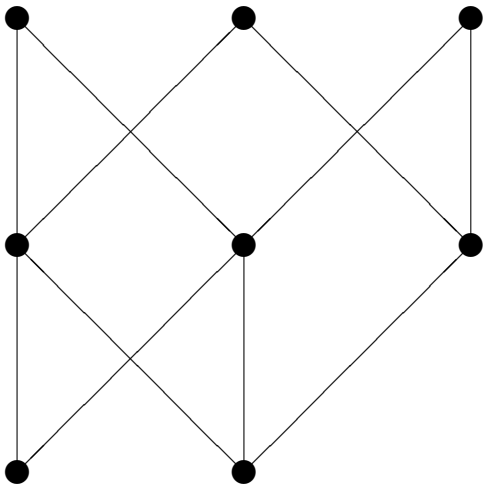
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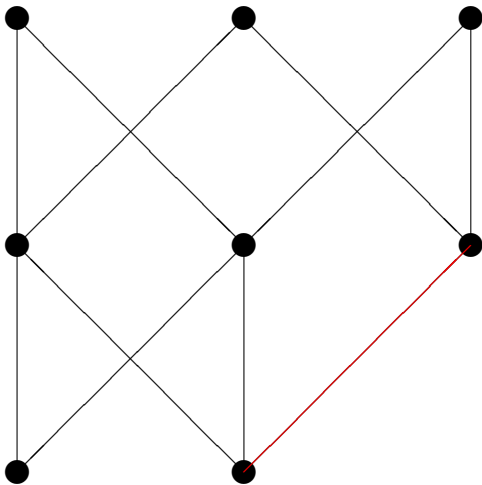


An Example

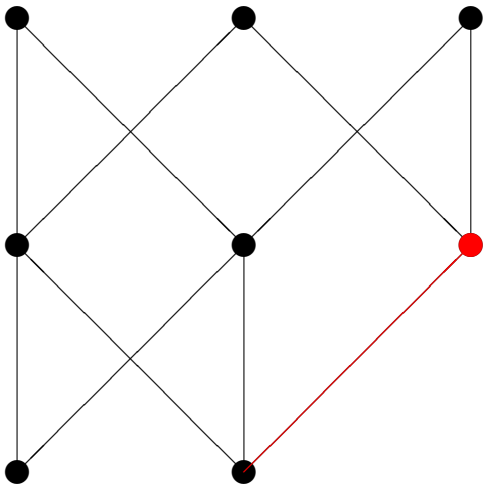
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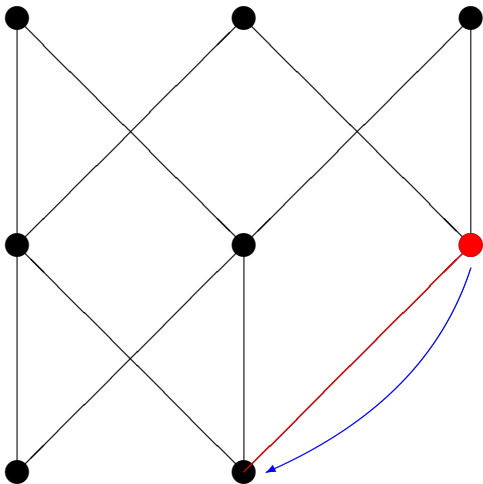
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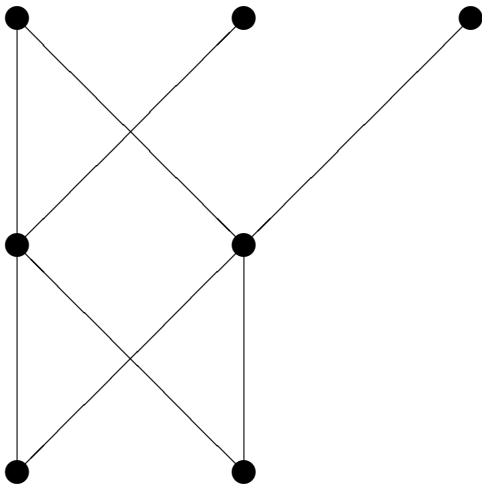
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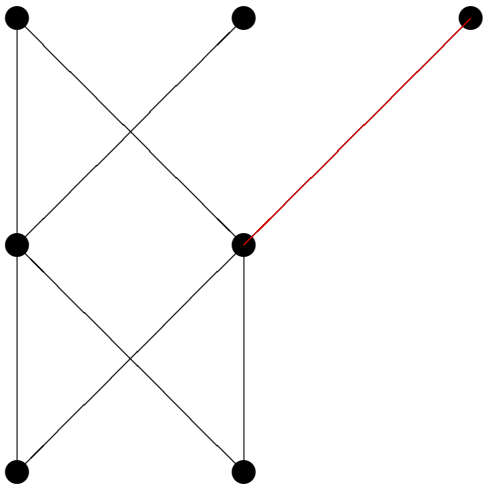
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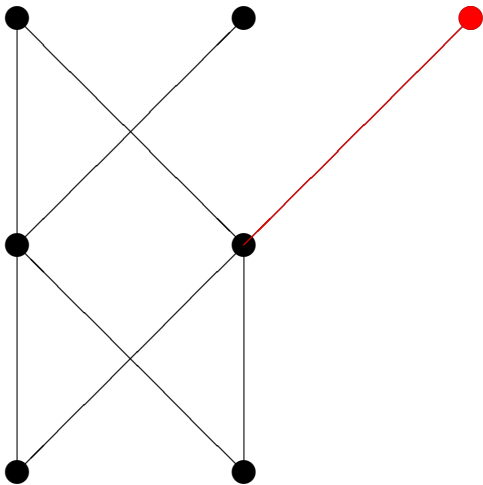
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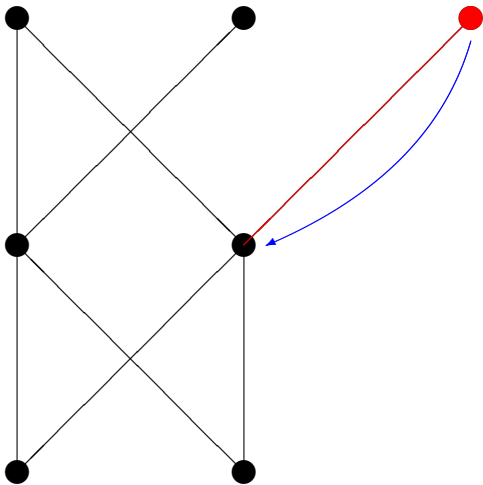
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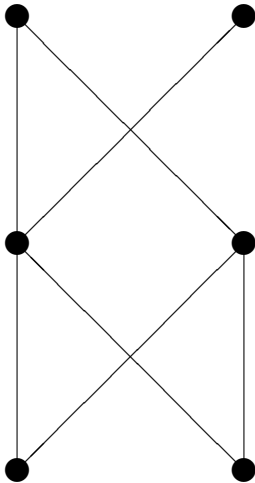
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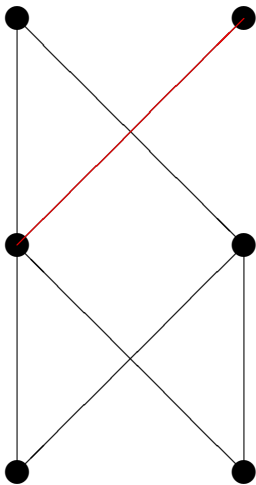
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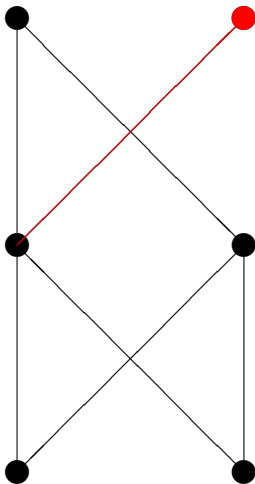
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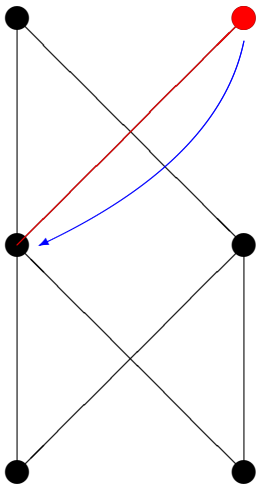
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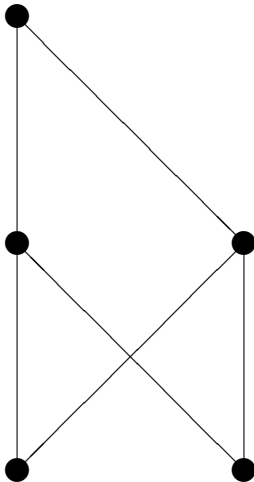
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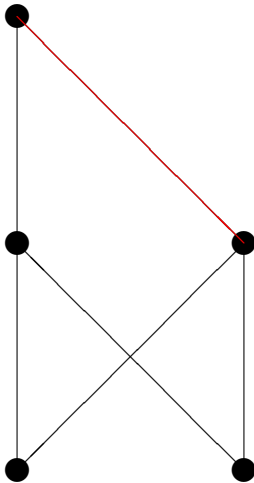
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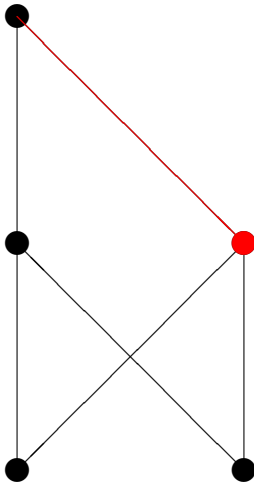
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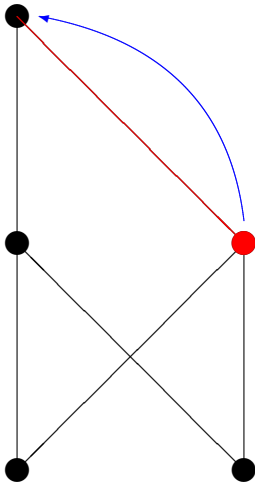
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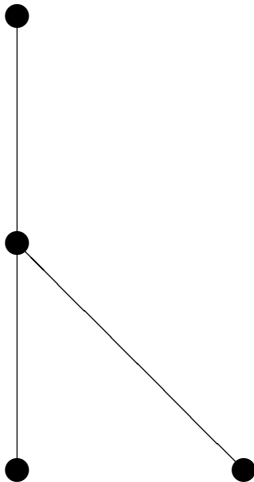
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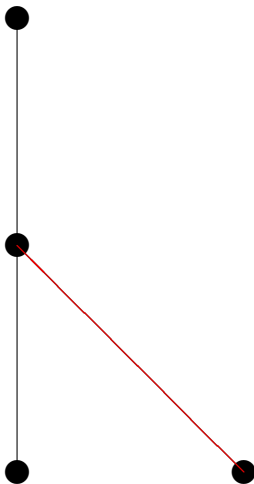
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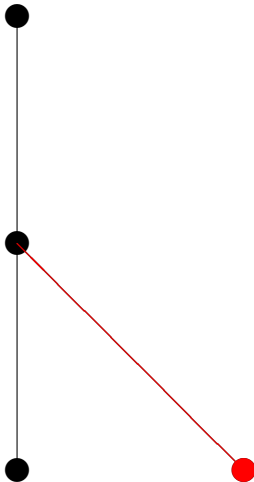
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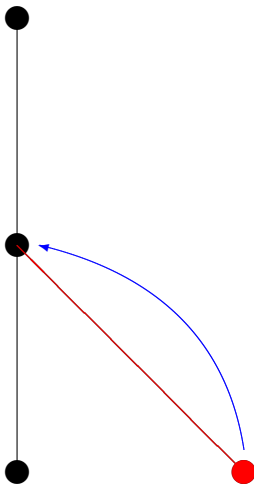
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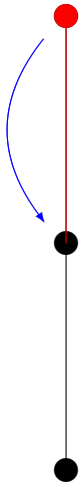
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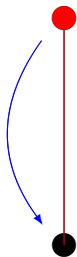
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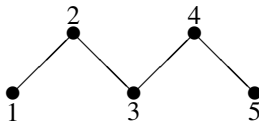
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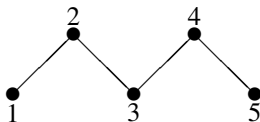
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The 5-fence

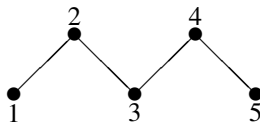


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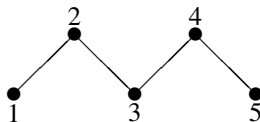
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Definition. A **binary constraint network** *consists of the following.*

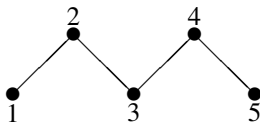
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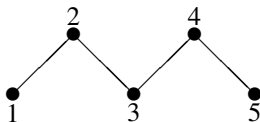
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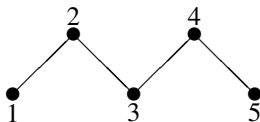
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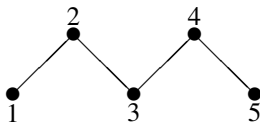
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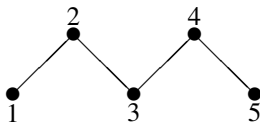
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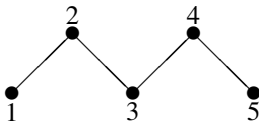
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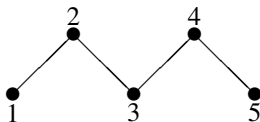
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 - ▶ For each set of variables we have at most one constraint.

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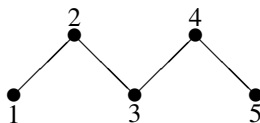


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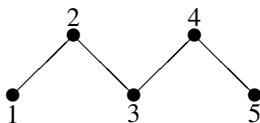
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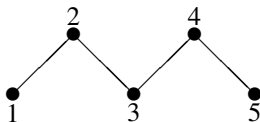
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Definition. For a given constraint network, let $Y \subseteq \{1, \dots, n\}$. Any element $a \in \prod_{j \in Y} D_j$ is an **instantiation** of the variables in Y . An instantiation is called **consistent** iff for all $i, j \in Y$ we have that $a_i \in C_i$ and $(a_i, a_j) \in C_{ij}$.

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Backtracking

Backtracking

The 5-fence

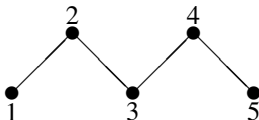
Backtracking

The 5-fence



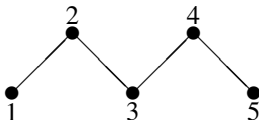
Backtracking

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Backtracking

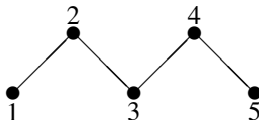
The 5-fence



FPP backtracking tree

Backtracking

The 5-fence

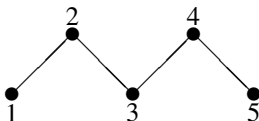


FPP backtracking tree

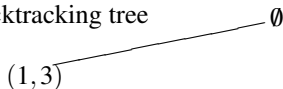
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Backtracking

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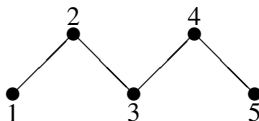


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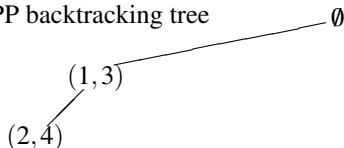


Backtracking

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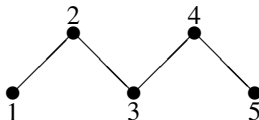


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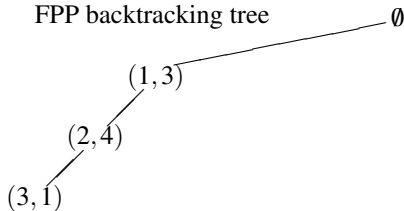


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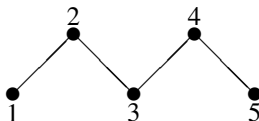


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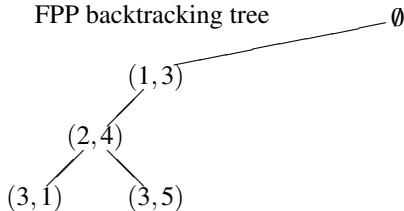


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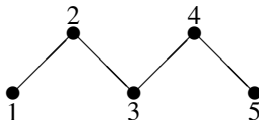


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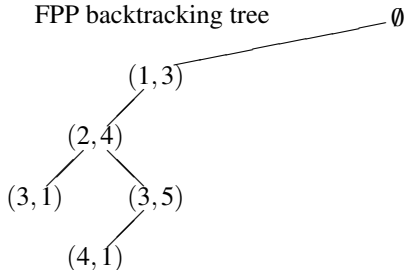


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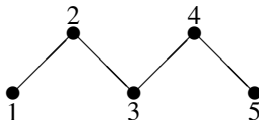


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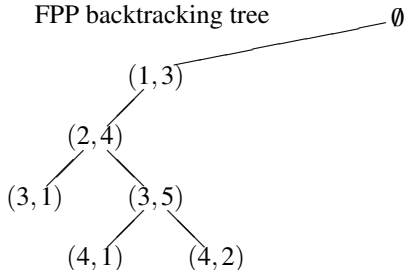


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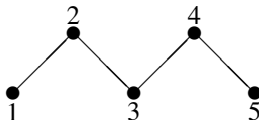


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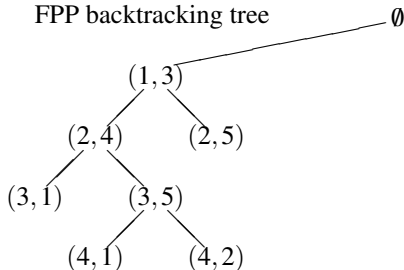


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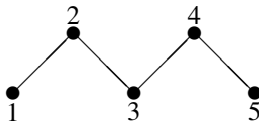


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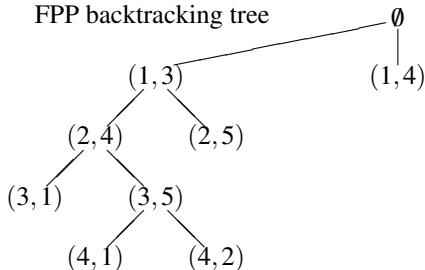


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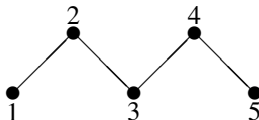


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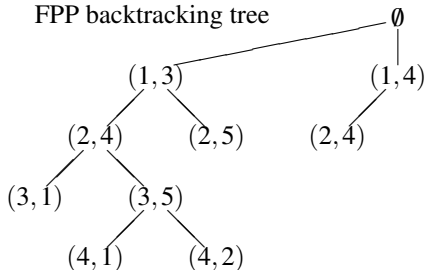


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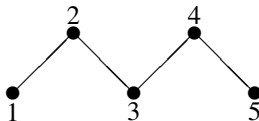


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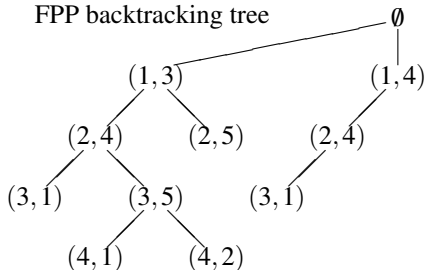


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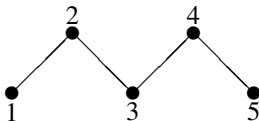


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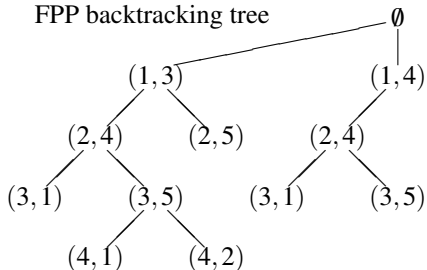


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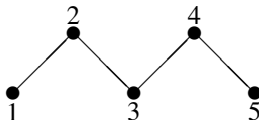


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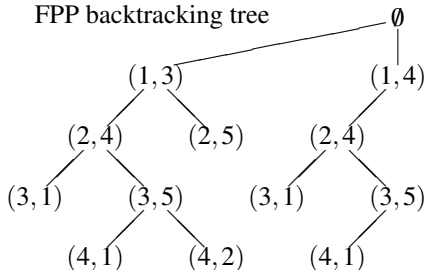


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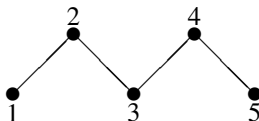


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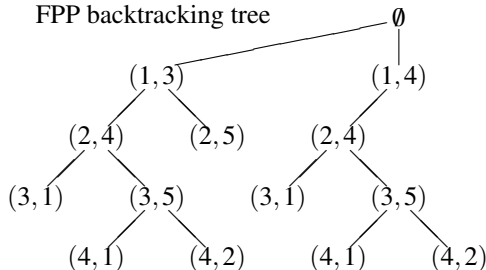


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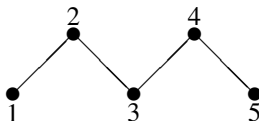


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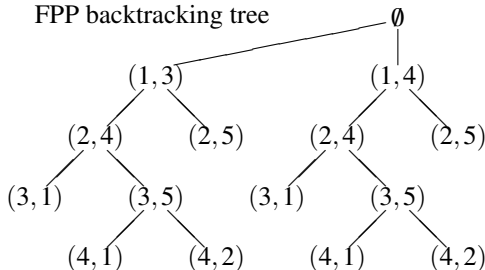


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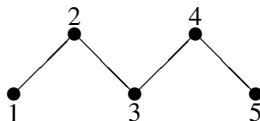


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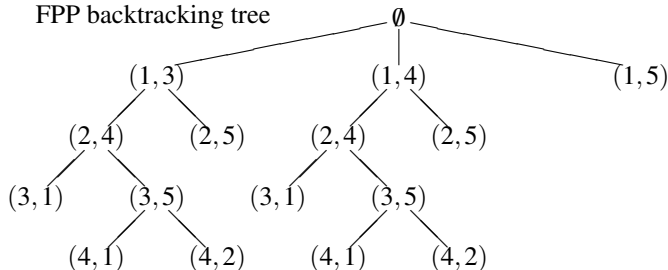


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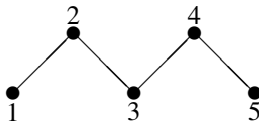


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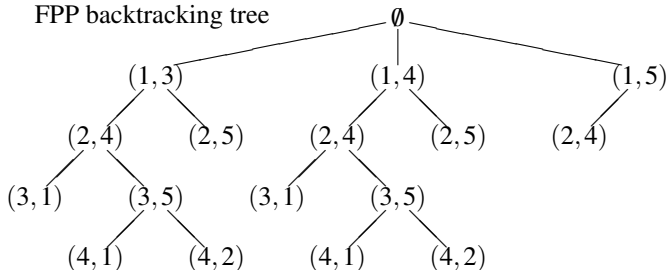


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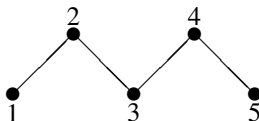


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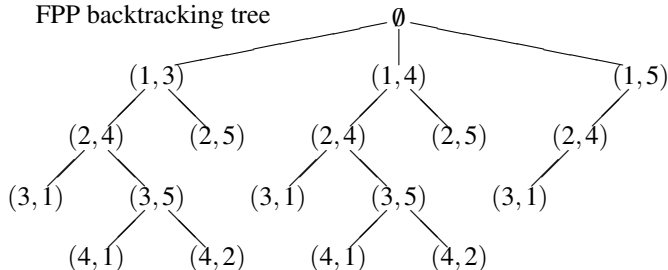


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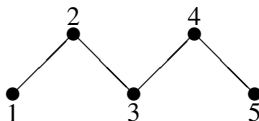


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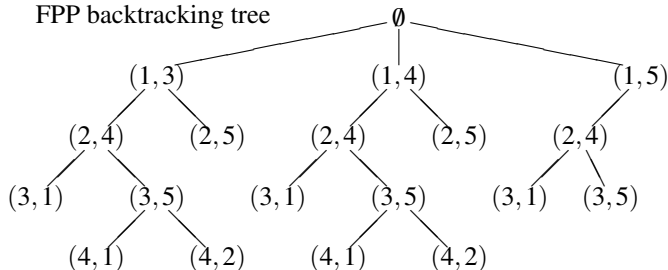


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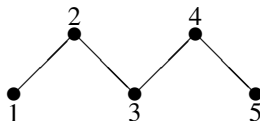


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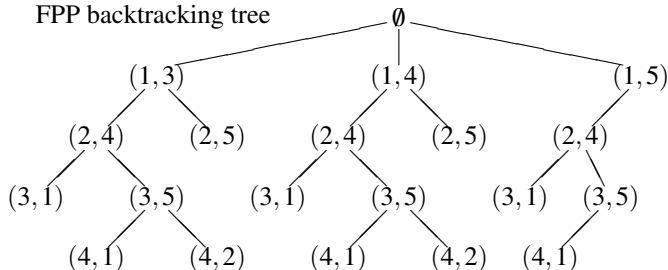


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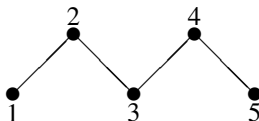


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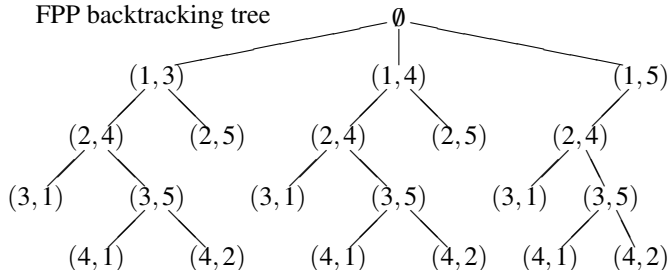


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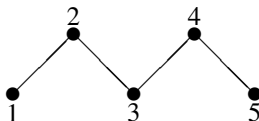


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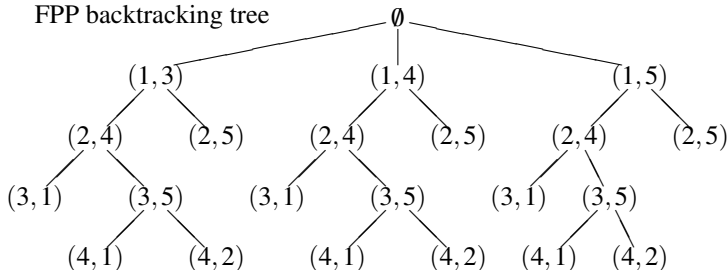


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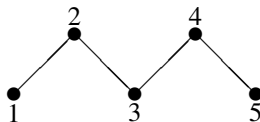


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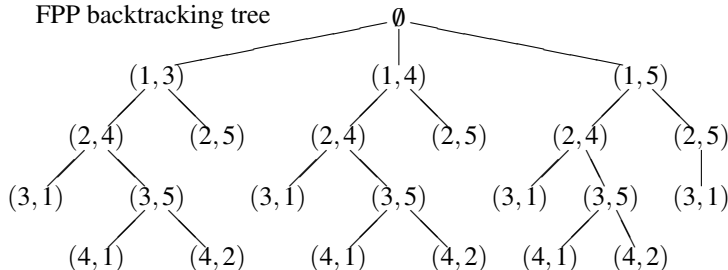


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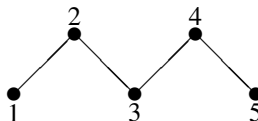


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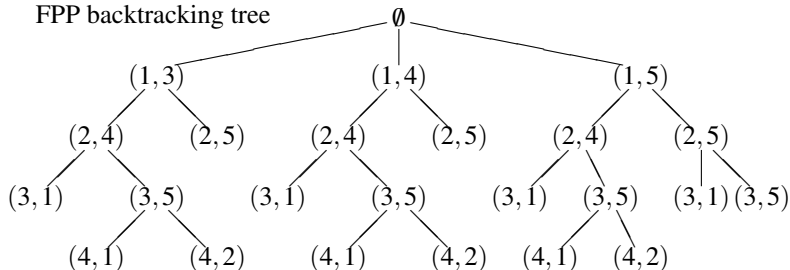


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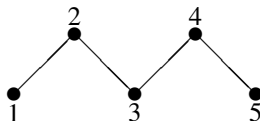


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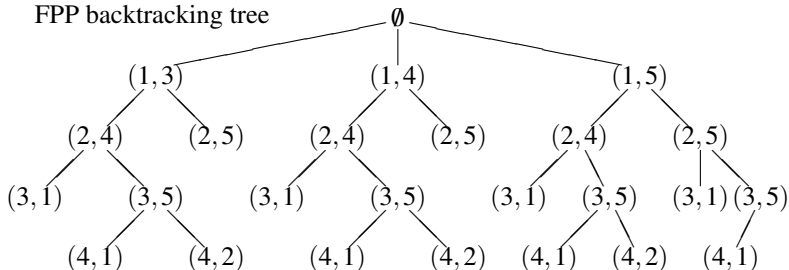


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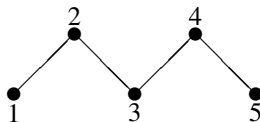


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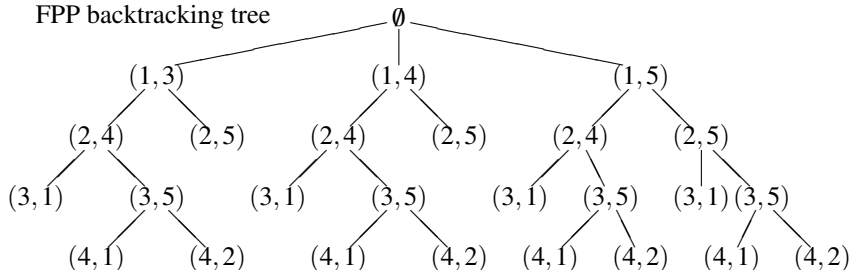


Backtracking

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FPP backtracking tree



Definition.

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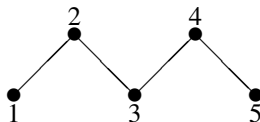
2-consistency is also called **arc consistency**,

3-consistency is also called **path consistency**.

A constraint network is **strongly k -consistent** iff for all $1 \leq j \leq k$ the network is j -consistent.

Enforcing Path Consistency

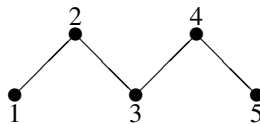
The 5-fence



Enforcing Path Consistency

The 5-fence

$(1,3) (1,4) (1,5)$



$(5,3)$ ●

$(5,2)$ ●

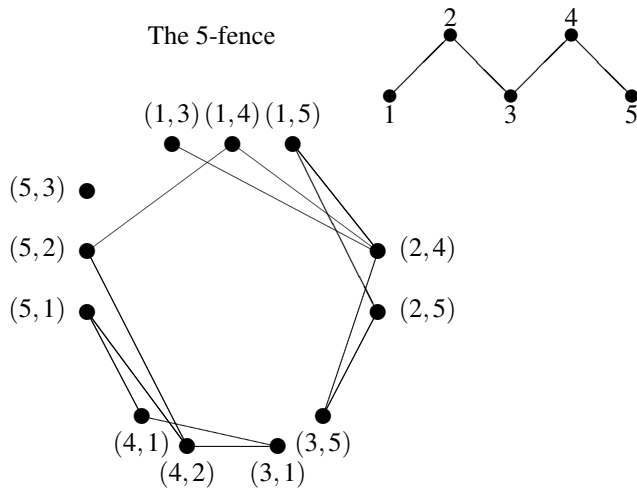
$(5,1)$ ●

● $(2,4)$

● $(2,5)$

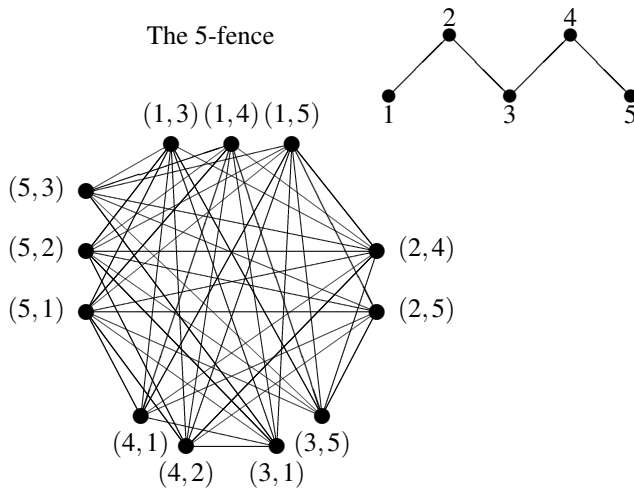
●
 $(4,1)$ ●
 $(4,2)$ ● $(3,5)$
 $(3,1)$

Enforcing Path Consistency



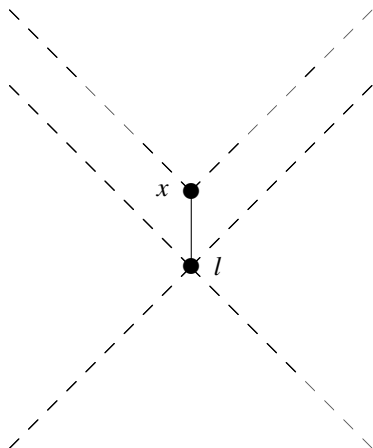
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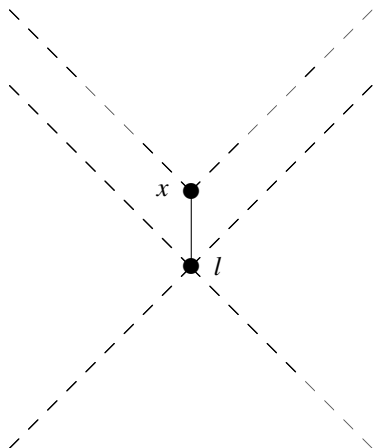


Irreducible Points are Irrelevant for Path Consistency

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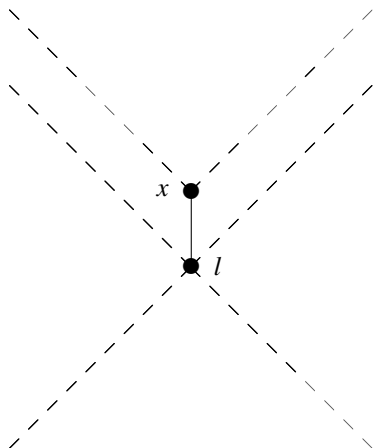


Irreducible Points are Irrelevant for Path Consistency



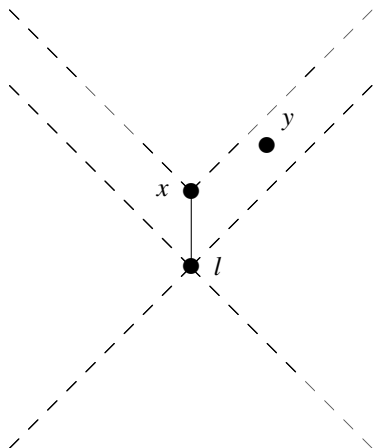
Let x have a unique lower cover l .

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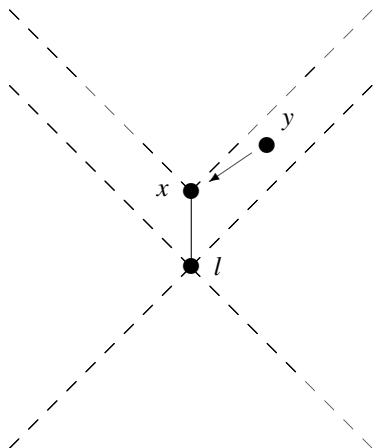
Let x have a unique lower cover l . Let $y > l$ and $y \not\geq x$.

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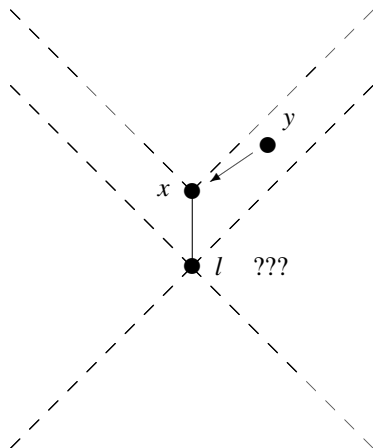
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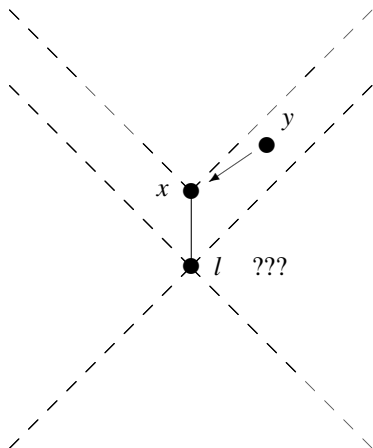
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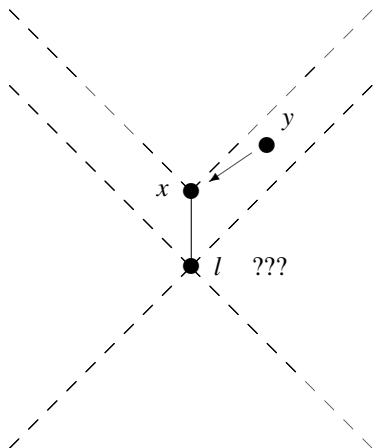
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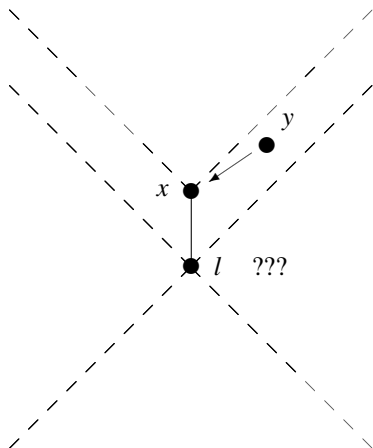
Let x have a unique lower cover l . Let $y > l$ and $y \not\geq x$. Then (y, x) is not consistent with any instantiation (l, \cdot)

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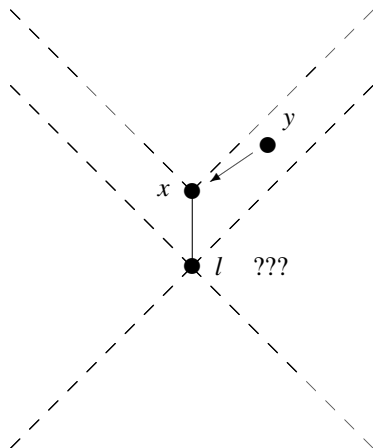


Let x have a unique lower cover l . Let $y > l$ and $y \not\geq x$. Then (y, x) is not consistent with any instantiation (l, \cdot) , so all edges incident with (y, x) can be eliminated.

Irreducible Points are Irrelevant for Path Consistency

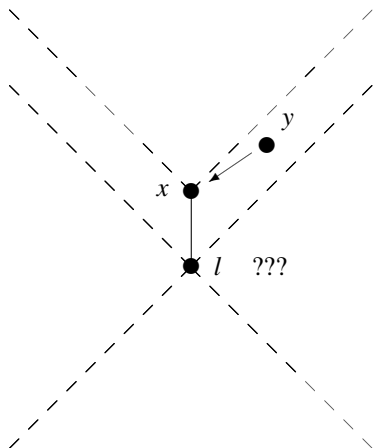


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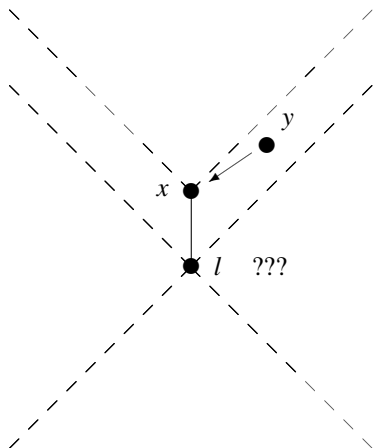
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Irreducible Points are Irrelevant for Path Consistency



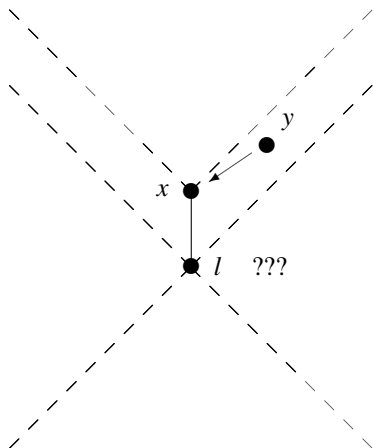
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Irreducible Points are Irrelevant for Path Consistency



For all other (z, x) , we have that, if $\{(a, b), (z, x)\}$ is an edge, then so is $\{(a, b), (z, l)\}$. Hence, (some details omitted) enforcing consistency on $EXPFPF(P)$ yields an empty network

Irreducible Points are Irrelevant for Path Consistency



For all other (z, x) , we have that, if $\{(a, b), (z, x)\}$ is an edge, then so is $\{(a, b), (z, l)\}$. Hence, (some details omitted) enforcing consistency on $EXPFPF(P)$ yields an empty network iff enforcing consistency on $EXPFPF(P \setminus \{x\})$ yields an empty network.

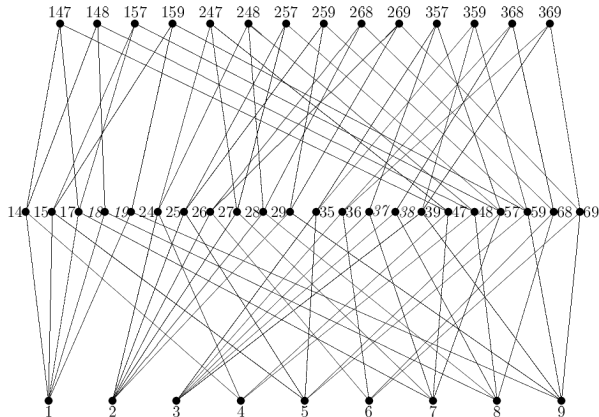
Open Question

Open Question

How strong is path consistency?

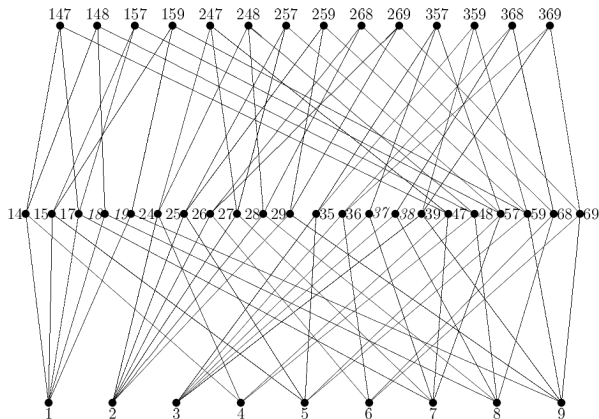
Open Question

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Program

Open Question

Can we get a similar result for removal of points with an acyclic neighborhood?

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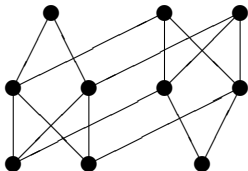
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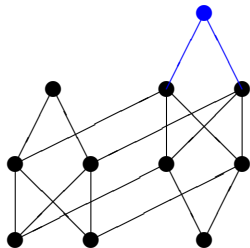
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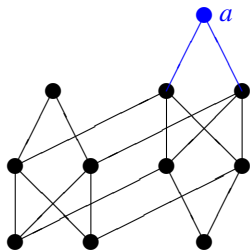
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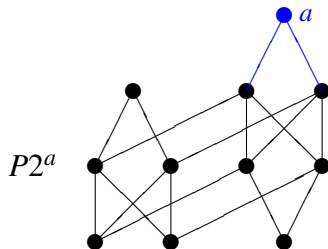
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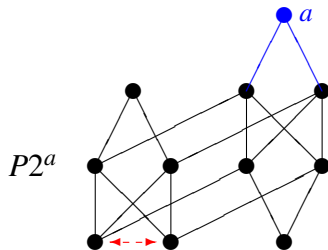
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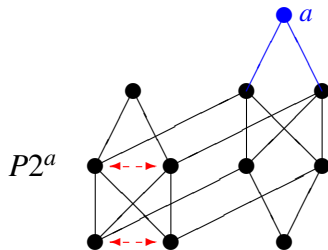
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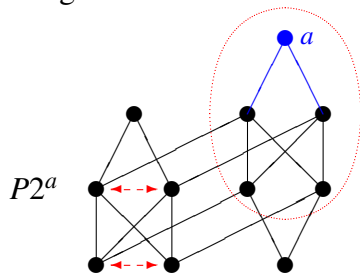
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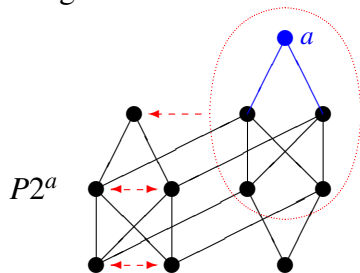
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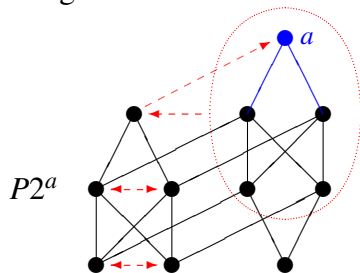
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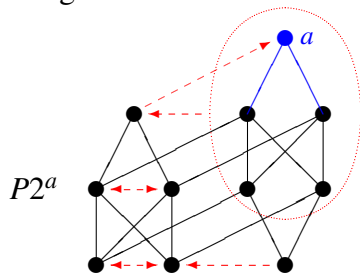
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2. Middle ground: Dimension 2 and fpp implies that enforcing path consistency produces an empty expanded (fpp) constraint network. The argument is combinatorial (but not “pointwise”). Does “collapsibility by retractable points” (and fpp) imply that enforcing path consistency produces an empty expanded (fpp) constraint network?

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Let's consider the topological side now.

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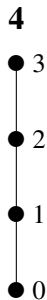
Definition. For an ordered set P , the complex with vertex set P and set of simplices \mathcal{S} being the set of totally ordered subsets is called the **chain complex** of P .

The Chain Complex

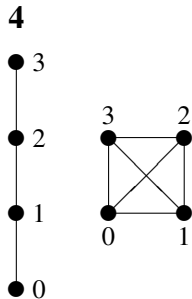
The Chain Complex



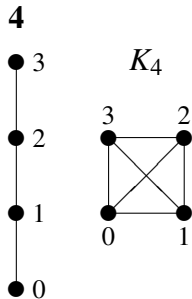
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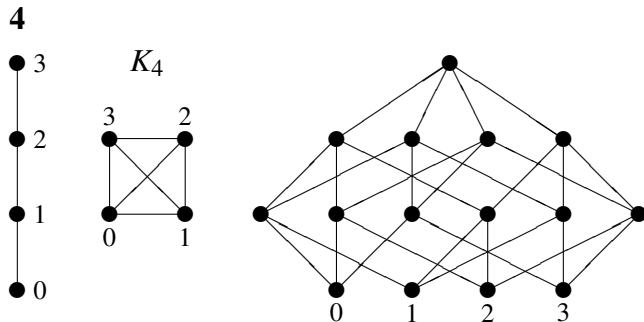
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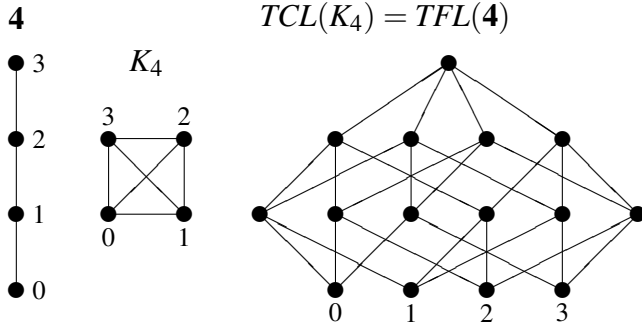
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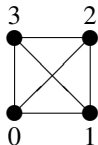


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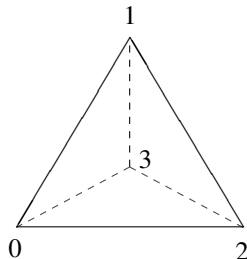
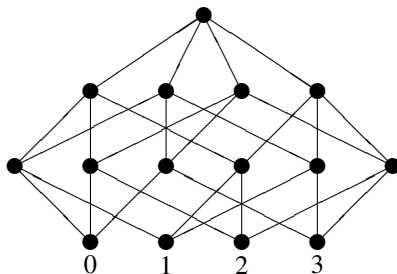


The Chain Complex

4

 K_4 

$$TCL(K_4) = TFL(4)$$



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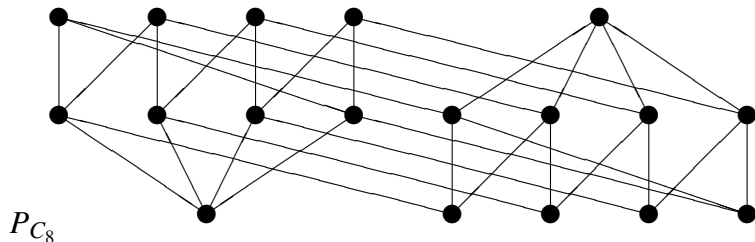
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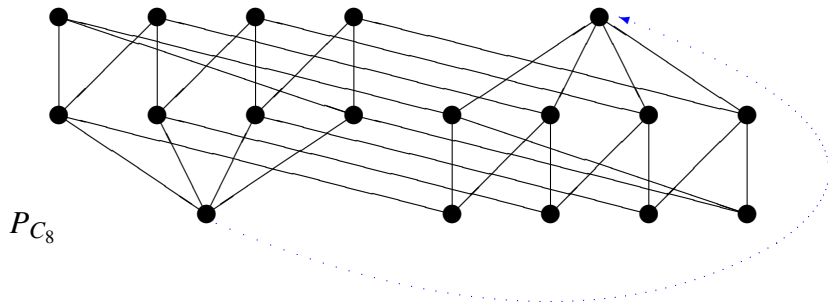
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FPP for $P \not\Rightarrow$ FSP for Chain Complex

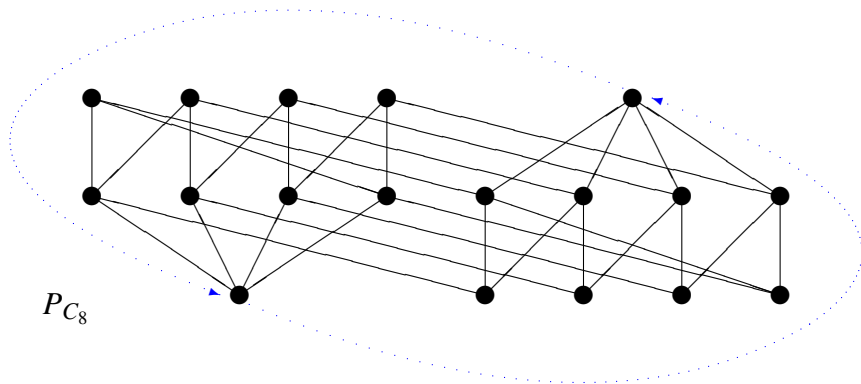
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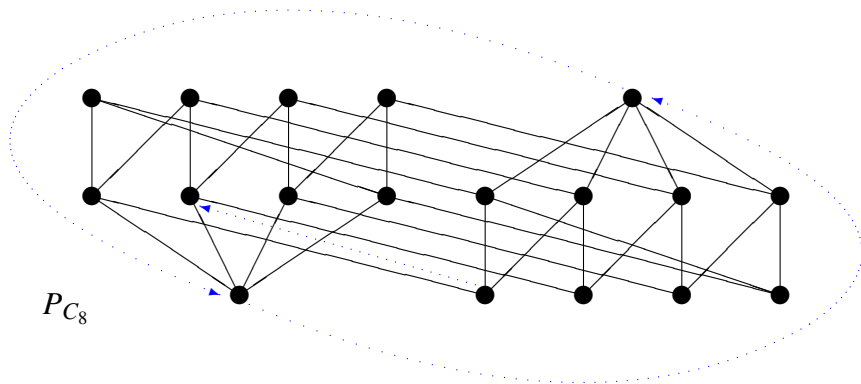
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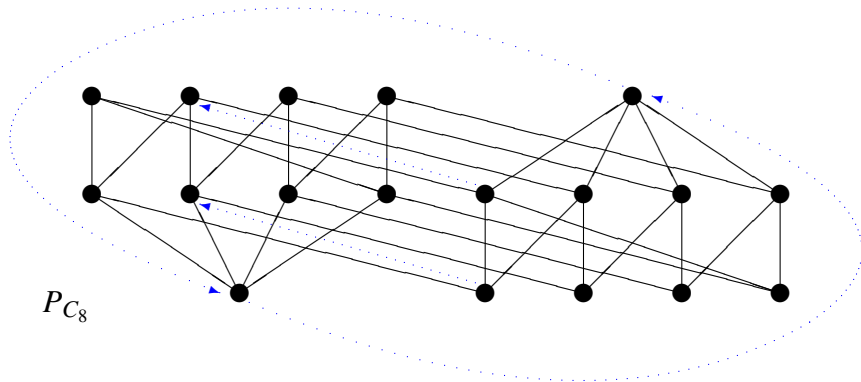
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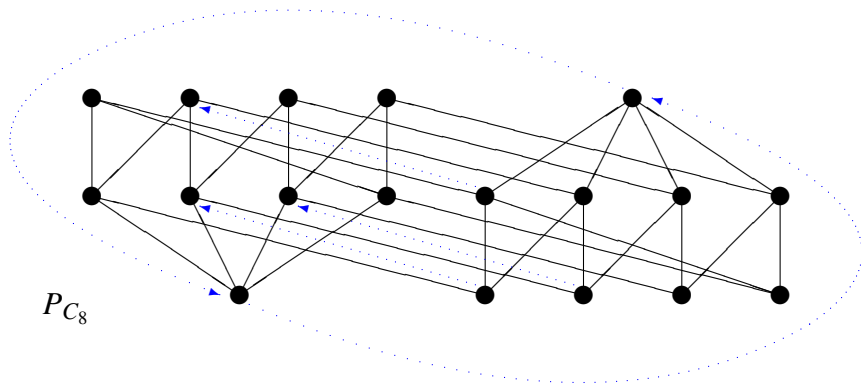
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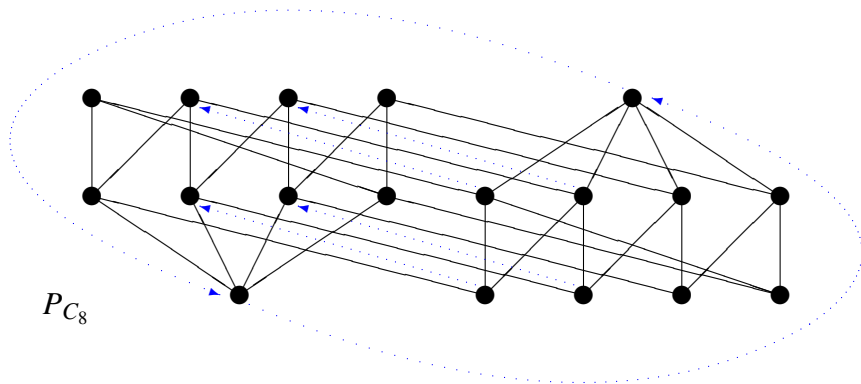
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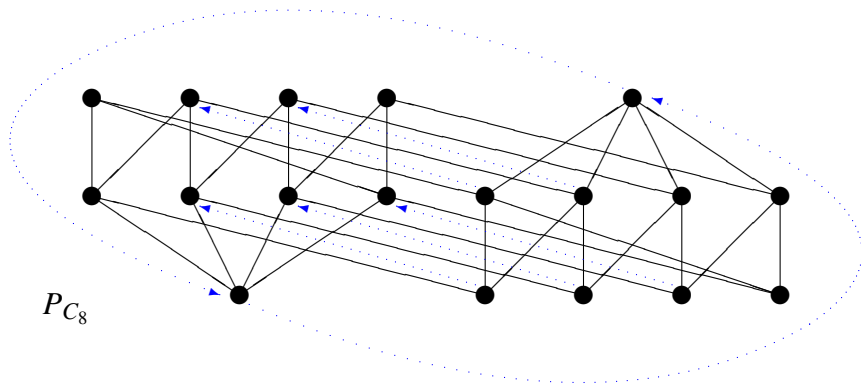
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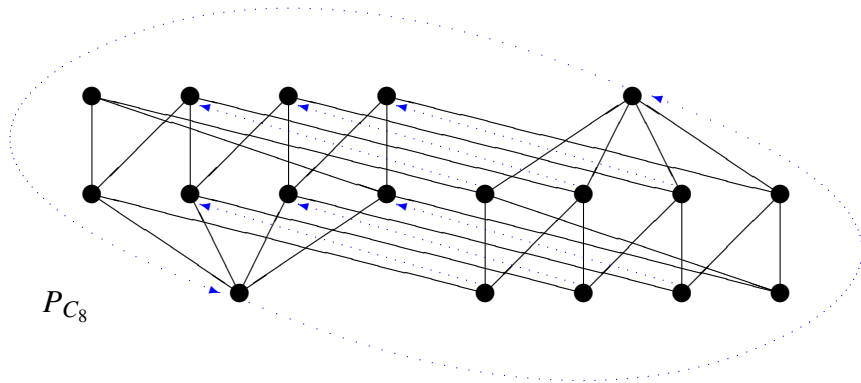
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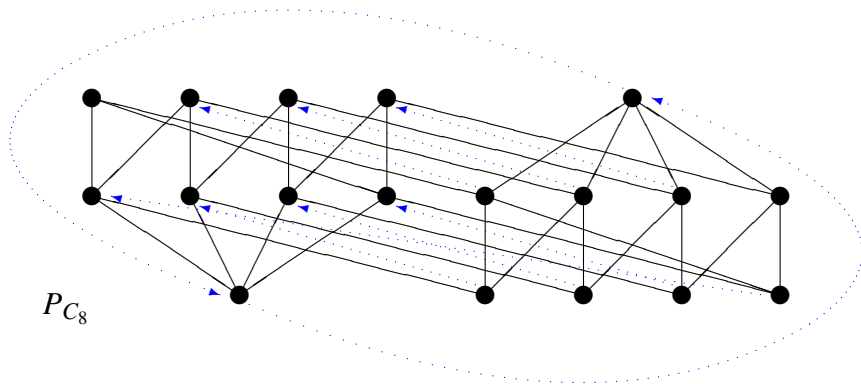
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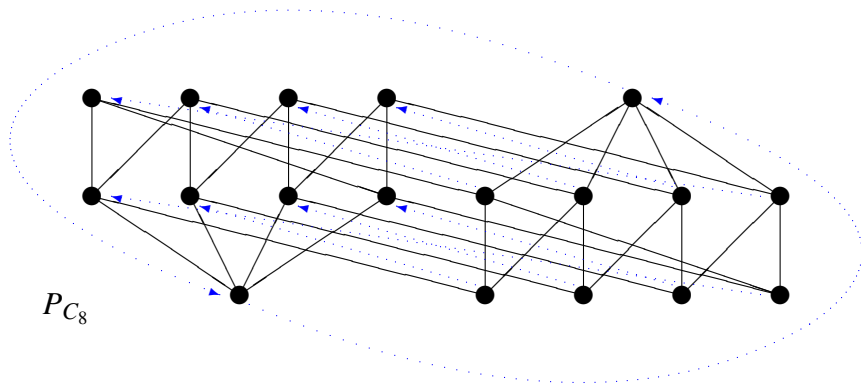
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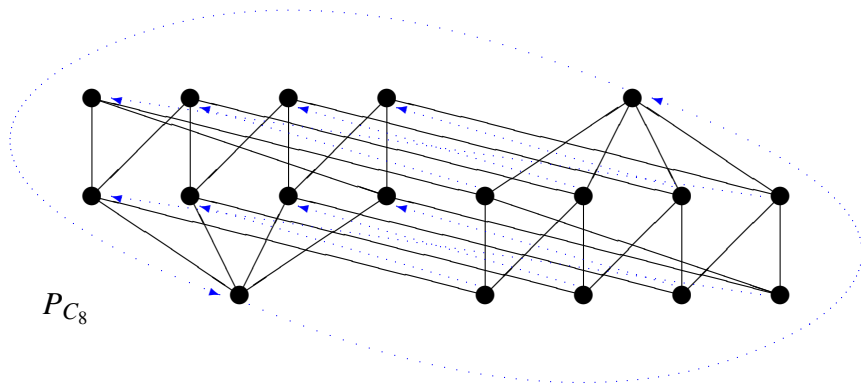
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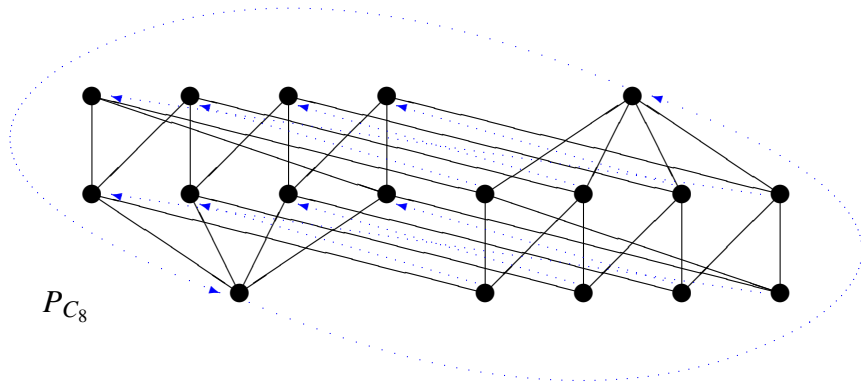


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Proposition. Let $K = (V, \mathcal{S})$ and $H = (W, \mathcal{T})$ be simplicial complexes and let $f : V \rightarrow W$ be a simplicial map. Then f can be extended to an affine map from $\mathcal{R}(K)$ to $\mathcal{R}(H)$.

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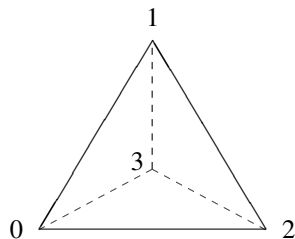
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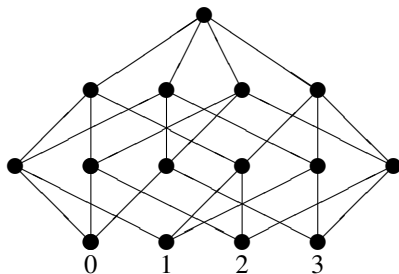
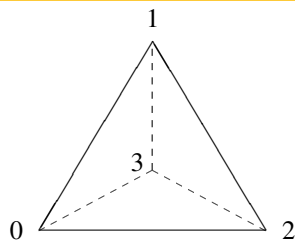
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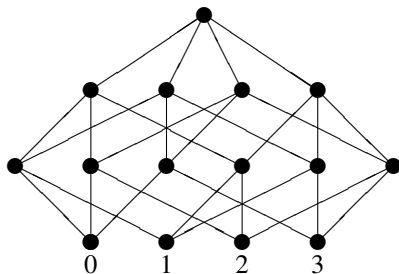
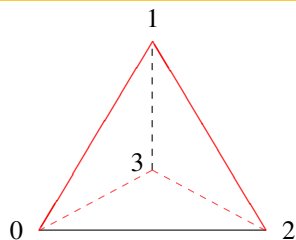
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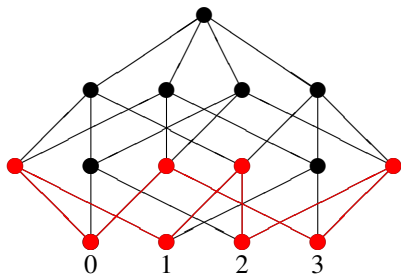
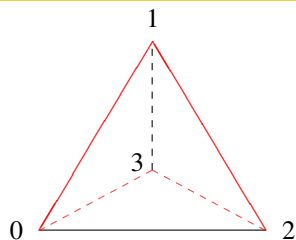
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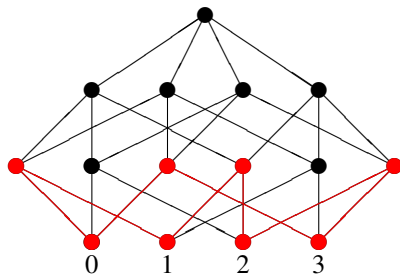
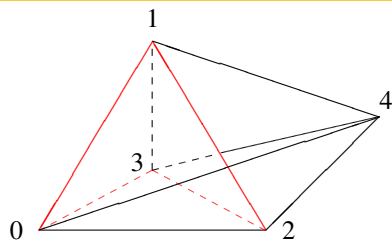
The affine map can only have a fixed point if it maps a simplex to itself.

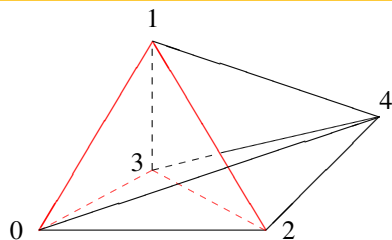




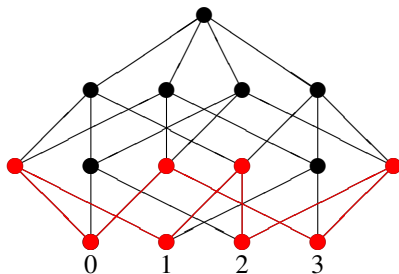


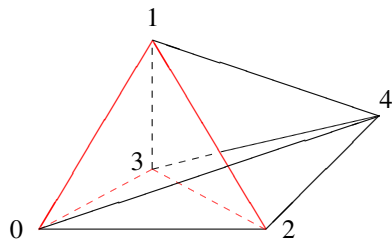




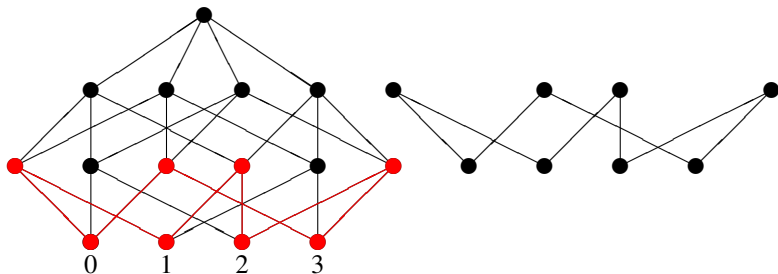


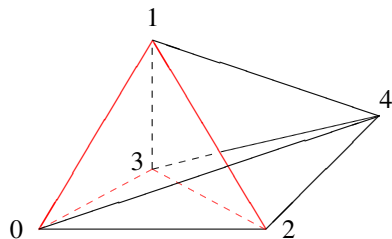
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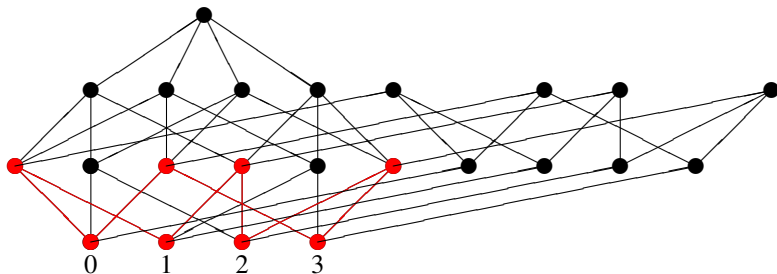


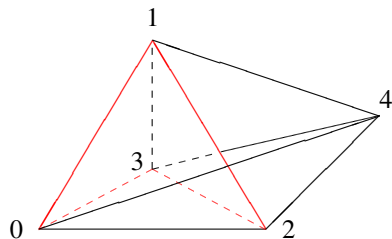
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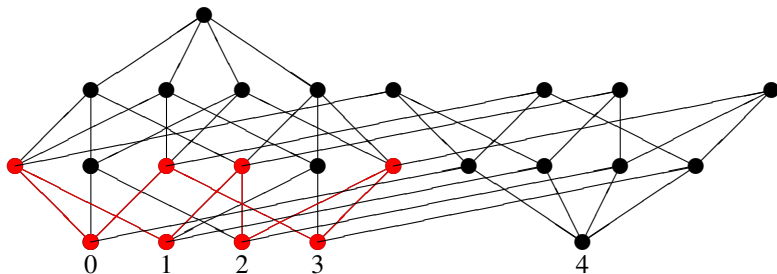


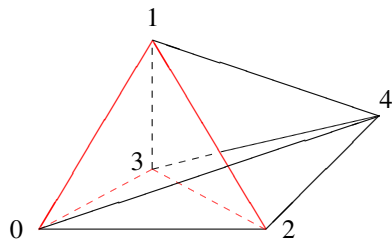
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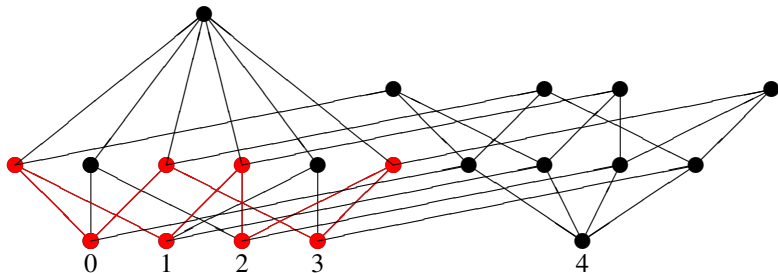


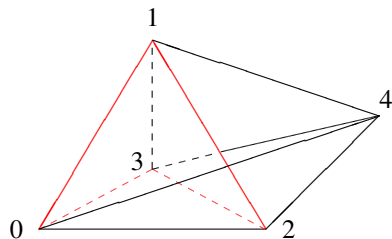
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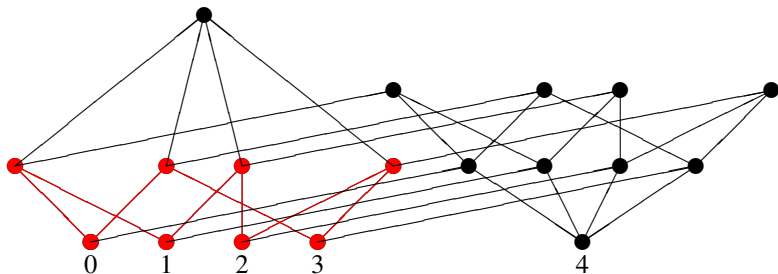


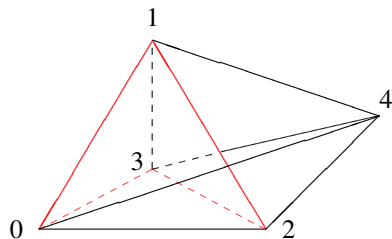
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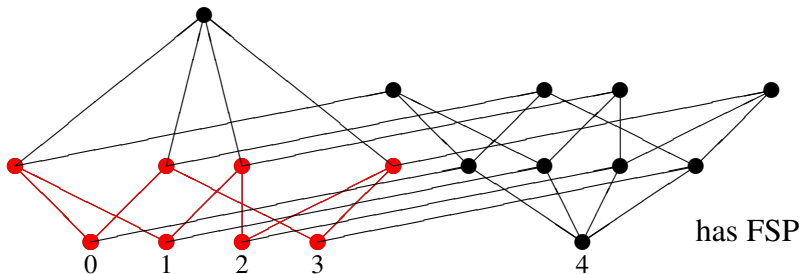


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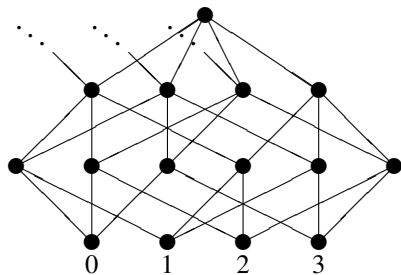
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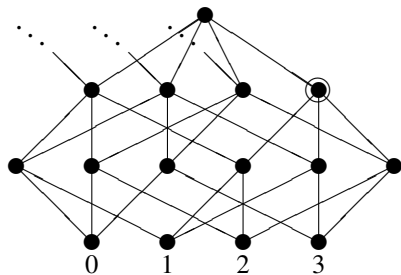
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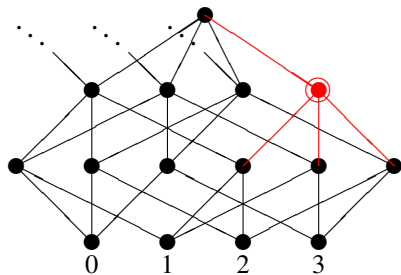
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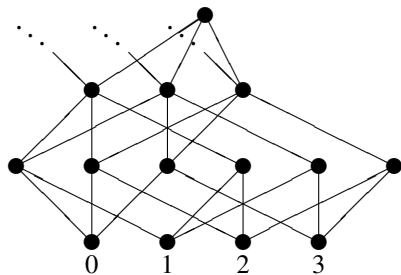
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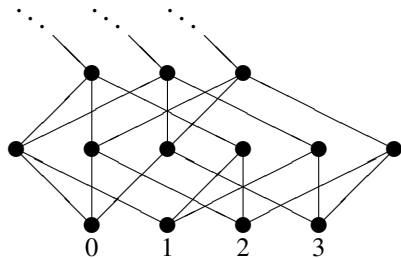
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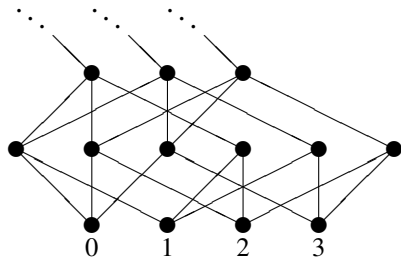
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4. K is called **collapsible** (in Whitehead's sense) iff K collapses to one of its vertices.

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Questions

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1. Is every *simplicial* retract of a collapsible simplicial complex collapsible?

Introduction

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1.

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Text

Example.

Example.

Example.

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Theorem.

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Proof.

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Example.

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